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2021.09 2024.06

2016.09 2020.07

(LH2020E094)

2021 12

MPC

MPC

1

2

MPC

Mongo ROS

2022 1 2022 4

Mongo

SSH

PC

ROS

ROS

Rviz

ROS

ROS Action

C

Matlab

Simulink

3Dmax

Linux

ROS

Microsoft Office

Xmind Visio

PLC

CET-6

Anti-swing control for davit systems based on hybrid force/position compliant impedance

Pendulation Reduction Control of Shipboard Crane Based on Adaptive Sliding Mode Variable Structure Approach